# BDTIC www.BDTIC.com/ATMEL

### Features

- Fast Read Access Time 70 ns
- Dual Voltage Range Operation
  - Low Voltage Power Supply Range, 3.0V to 3.6V
  - or Standard 5V  $\pm$  10% Supply Range
- Compatible with JEDEC Standard AT27C010
- Low Power CMOS Operation
  - 20  $\mu A$  Max (Less than 1  $\mu A$  Typical) Standby for  $V_{CC}$  = 3.6V
  - 29 mW Max Active at 5 MHz for  $V_{CC}$  = 3.6V
- JEDEC Standard Packages
  - 32-lead PLCC
  - 32-lead TSOP
  - 32-lead VSOP
- High Reliability CMOS Technology
  - 2,000V ESD Protection
  - 200 mA Latchup Immunity
- Rapid Programming Algorithm –100 µs/Byte (Typical)
- CMOS and TTL Compatible Inputs and Outputs – JEDEC Standard for LVTTL
- Integrated Product Identification Code
- Industrial Temperature Range
- Green (Pb/Halide-free) Packaging Option

# 1. Description

The AT27LV010A is a high-performance, low-power, low-voltage 1,048,576-bit onetime programmable read-only memory (OTP EPROM) organized as 128K by 8 bits. It requires only one supply in the range of 3.0V to 3.6V in normal read mode operation, making it ideal for fast, portable systems using battery power.

Atmel's innovative design techniques provide fast speeds that rival 5V parts while keeping the low power consumption of a 3.3V supply. At  $V_{CC} = 3.0V$ , any byte can be accessed in less than 70 ns. With a typical power dissipation of only 18 mW at 5 MHz and  $V_{CC} = 3.3V$ , the AT27LV010A consumes less than one fifth the power of a standard 5V EPROM. Standby mode supply current is typically less than 1  $\mu$ A at 3.3V.

The AT27LV010A is available in industry-standard JEDEC-approved one-time programmable (OTP) plastic PLCC and TSOP packages. All devices feature two-line control ( $\overline{CE}$ ,  $\overline{OE}$ ) to give designers the flexibility to prevent bus contention.

The AT27LV010A operating with V<sub>CC</sub> at 3.0V produces TTL level outputs that are compatible with standard TTL logic devices operating at V<sub>CC</sub> = 5.0V. The device is also capable of standard 5-volt operation making it ideally suited for dual supply range systems or card products that are pluggable i-n both 3-volt and 5-volt hosts.

Atmel's AT27LV010A has additional features to ensure high quality and efficient production use. The Rapid Programming Algorithm reduces the time required to program the part and guarantees reliable programming. Programming time is typically only 100  $\mu$ s/byte. The Integrated Product Identification Code electronically identifies the device and manufacturer. This feature is used by industry-standard programming equipment to select the proper programming algorithms and voltages. The AT27LV010A programs exactly the same way as a standard 5V AT27C010 and uses the same programming equipment.



1-Megabit (128K x 8) Low Voltage OTP EPROM

# AT27LV010A

0548E-EPROM-12/07

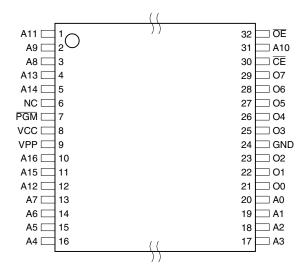
http://www.BDTIC.com/ATMEI



### 2. Pin Configurations

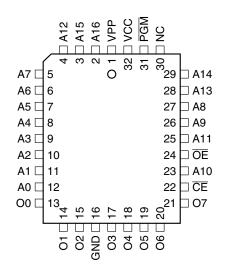
| Pin Name | Function       |
|----------|----------------|
| A0 - A16 | Addresses      |
| 00 - 07  | Outputs        |
| CE       | Chip Enable    |
| ŌĒ       | Output Enable  |
| PGM      | Program Strobe |
| NC       | No Connect     |

#### 2.1 32-lead TSOP/VSOP (Type 1) Top View



#### 2.2 32-lead PLCC Top View

2

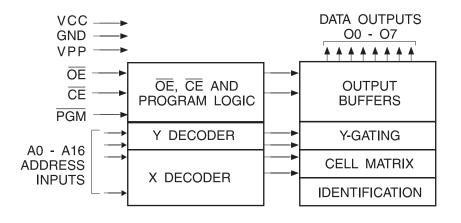


# AT27LV010A http://www.BDTIC.com/ATMEL

#### 3. System Considerations

Switching between active and standby conditions via the Chip Enable pin may produce transient voltage excursions. Unless accommodated by the system design, these transients may exceed datasheet limits, resulting in device non-conformance. At a minimum, a 0.1  $\mu$ F high frequency, low inherent inductance, ceramic capacitor should be utilized for each device. This capacitor should be connected between the V<sub>CC</sub> and Ground terminals of the device, as close to the device as possible. Additionally, to stabilize the supply voltage level on printed circuit boards with large EPROM arrays, a 4.7  $\mu$ F bulk electrolytic capacitor should be utilized, again connected between the V<sub>CC</sub> and Ground terminals. This capacitor should be positioned as close as possible to the point where the power supply is connected to the array.

#### 4. Block Diagram



DTIC.com/AT

# 5. Absolute Maximum Ratings\*

| Temperature Under Bias                                   | 40°C to +85°C                 |
|--|-------------------------------|
| Storage Temperature                                      | 65°C to +125°C                |
| Voltage on Any Pin with<br>Respect to Ground             | 2.0V to +7.0V <sup>(1)</sup>  |
| Voltage on A9 with<br>Respect to Ground                  | 2.0V to +14.0V <sup>(1)</sup> |
| V <sub>PP</sub> Supply Voltage with<br>Respect to Ground | 2.0V to +14.0V <sup>(1)</sup> |

://www.]

\*NOTICE: Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability

Note: 1. Minimum voltage is -0.6V DC which may undershoot to -2.0V for pulses of less than 20 ns. Maximum output pin voltage is V<sub>CC</sub> + 0.75V DC which may be exceeded if certain precautions are observed (consult application notes) and which may overshoot to +7.0V for pulses of less than 20 ns.



# 6. Operating Modes

| Mode/Pin                                 | CE              | ŌE              | PGM              | Ai  | V <sub>PP</sub> | V <sub>cc</sub> | Outputs             |
|--|-----------------|-----------------|------------------|---|-----------------|-----------------|---------------------|
| Read <sup>(2)</sup>                      | V <sub>IL</sub> | V <sub>IL</sub> | X <sup>(1)</sup> | Ai  | х               | V <sub>CC</sub> | D <sub>OUT</sub>    |
| Output Disable <sup>(2)</sup>            | Х               | V <sub>IH</sub> | Х                | х   | х               | V <sub>CC</sub> | High Z              |
| Standby <sup>(2)</sup>                   | V <sub>IH</sub> | Х               | Х                | х   | Х               | V <sub>CC</sub> | High Z              |
| Rapid Program <sup>(3)</sup>             | V <sub>IL</sub> | V <sub>IH</sub> | V <sub>IL</sub>  | Ai  | V <sub>PP</sub> | V <sub>CC</sub> | D <sub>IN</sub>     |
| PGM Verify <sup>(3)</sup>                | V <sub>IL</sub> | V <sub>IL</sub> | V <sub>IH</sub>  | Ai  | $V_{PP}$        | V <sub>CC</sub> | D <sub>OUT</sub>    |
| PGM Inhibit <sup>(3)</sup>               | V <sub>IH</sub> | Х               | Х                | х   | $V_{PP}$        | V <sub>CC</sub> | High Z              |
| Product Identification <sup>(3)(5)</sup> | V <sub>IL</sub> | V <sub>IL</sub> | х                | $A9 = V_{H}^{(4)}$ $A0 = V_{IH} \text{ or } V_{IL}$ $A1 - A16 = V_{IL}$ | х               | V <sub>cc</sub> | Identification Code |

Notes: 1. X can be  $V_{IL}$  or  $V_{IH}$ .

2. Read, output disable, and standby modes require,  $3.0V \leq V_{CC} \leq 3.6V$ , or  $4.5V \leq V_{CC} \leq 5.5V$ .

3. Refer to Programming Characteristics. Programming modes require  $V_{CC} = 6.5V$ .

4.  $V_{H} = 12.0 \pm 0.5 V.$ 

 Two identifier bytes may be selected. All Ai inputs are held low (V<sub>IL</sub>), except A9 which is set to V<sub>H</sub> and A0 which is toggled low (V<sub>IL</sub>) to select the Manufacturer's Identification byte and high (V<sub>IH</sub>) to select the Device Code byte.

# 7. DC and AC Operating Conditions for Read Operation

|   | AT27LV010A-70 |
|---|---------------|
| Industrial Operating Temperature (Case) | -40°C - 85°C  |
|   | 3.0V to 3.6V  |
| V <sub>CC</sub> Power Supply            | 5V ±10%       |

http://www.BDTIC.com/ATI

# AT27LV010A

4

AT27LV010A

#### 8. DC and Operating Characteristics for Read Operation

| Symbol                          | Parameter   | Condition   | Min  | Max                   | Units |
|---------------------------------|---|---|------|-----------------------|-------|
| $V_{\rm CC} = 3.0V$             | ' to 3.6V   |   |      |                       |       |
| ILI                             | Input Load Current                                  | $V_{IN} = 0V$ to $V_{CC}$                                 |      | ±1                    | μA    |
| I <sub>LO</sub>                 | Output Leakage Current                              | $V_{OUT} = 0V$ to $V_{CC}$                                |      | ±5                    | μA    |
| I <sub>PP1</sub> <sup>(2)</sup> | V <sub>PP</sub> <sup>(1)</sup> Read/Standby Current | $V_{PP} = V_{CC}$   |      | 10                    | μA    |
|                                 | ) ( (1) Otomoliny Osymptot                          | $I_{SB1}$ (CMOS), $\overline{CE} = V_{CC \pm} 0.3V$       |      | 20                    | μA    |
| I <sub>SB</sub>                 | V <sub>CC</sub> <sup>(1)</sup> Standby Current      | $I_{SB2}$ (TTL), $\overline{CE} = 2.0$ to $V_{CC} + 0.5V$ |      | 100                   | μA    |
| I <sub>CC</sub>                 | V <sub>CC</sub> Active Current                      | f = 5 MHz, $I_{OUT}$ = 0 mA, $\overline{CE} = V_{IL}$     |      | 8                     | mA    |
| V <sub>IL</sub>                 | Input Low Voltage                                   |   | -0.6 | 0.8                   | V     |
| V <sub>IH</sub>                 | Input High Voltage                                  |   | 2.0  | V <sub>CC</sub> + 0.5 | V     |
| V <sub>OL</sub>                 | Output Low Voltage                                  | I <sub>OL</sub> = 2.0 mA                                  |      | 0.4                   | V     |
| V <sub>OH</sub>                 | Output High Voltage                                 | I <sub>OH</sub> = -2.0 mA                                 | 2.4  |                       | V     |
| $V_{\rm CC} = 4.5 V$            | ′ to 5.5V   |   |      |                       |       |
| I <sub>LI</sub>                 | Input Load Current                                  | $V_{IN} = 0V$ to $V_{CC}$                                 |      | ±1                    | μA    |
| I <sub>LO</sub>                 | Output Leakage Current                              | $V_{OUT} = 0V$ to $V_{CC}$                                |      | ±5                    | μA    |
| I <sub>PP1</sub> <sup>(2)</sup> | V <sub>PP</sub> <sup>(1)</sup> Read/Standby Current | $V_{PP} = V_{CC}$   |      | 10                    | μA    |
|                                 | V <sub>CC</sub> <sup>(1)</sup> Standby Current      | $I_{SB1}$ (CMOS), $\overline{CE} = V_{CC} \pm 0.3V$       |      | 100                   | μA    |
| I <sub>SB</sub>                 |   | $I_{SB2}$ (TTL), $\overline{CE}$ = 2.0 to $V_{CC}$ + 0.5V |      | 1                     | mA    |
| I <sub>CC</sub>                 | V <sub>CC</sub> Active Current                      | f = 5 MHz, $I_{OUT}$ = 0 mA, $\overline{CE}$ = $V_{IL}$   |      | 25                    | mA    |
| V <sub>IL</sub>                 | Input Low Voltage                                   |   | -0.6 | 0.8                   | V     |
| V <sub>IH</sub>                 | Input High Voltage                                  |   | 2.0  | V <sub>CC</sub> + 0.5 | V     |
| V <sub>OL</sub>                 | Output Low Voltage                                  | I <sub>OL</sub> = 2.1 mA                                  |      | 0.4                   | V     |
| V <sub>OH</sub>                 | Output High Voltage                                 | I <sub>OH</sub> = -400 μA                                 | 2.4  |                       | V     |

Notes: 1. V<sub>CC</sub> must be applied simultaneously with or before V<sub>PP</sub> and removed simultaneously with or after V<sub>PP</sub>

2. V<sub>PP</sub> may be connected directly to V<sub>CC</sub>, except during programming. The supply current would then be the sum of I<sub>CC</sub> and I<sub>PP</sub>



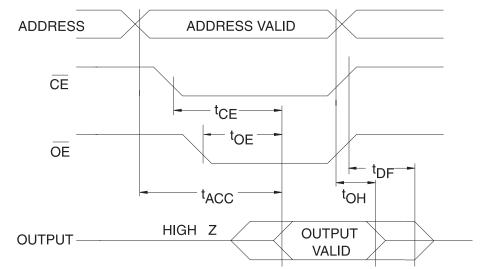


# 9. AC Characteristics for Read Operation

 $V_{CC}$  = 3.0V to 3.6V and 4.5V to 5.5V

|                                   |   |  | AT27LV010A-70 |     |       |
|-----------------------------------|---|--|---------------|-----|-------|
| Symbol                            | Parameter   | Condition                                | Min           | Max | Units |
| t <sub>ACC</sub> <sup>(3)</sup>   | Address to Output Delay   | $\overline{CE} = \overline{OE} = V_{IL}$ |               | 70  | ns    |
| t <sub>CE</sub> <sup>(2)</sup>    | CE to Output Delay  | $\overline{OE} = V_{IL}$                 |               | 70  | ns    |
| t <sub>OE</sub> <sup>(2)(3)</sup> | OE to Output Delay  | $\overline{CE} = V_{IL}$                 |               | 40  | ns    |
| t <sub>DF</sub> <sup>(4)(5)</sup> | OE or CE High to Output Float, Whichever<br>Occurred First                              |  |               | 35  | ns    |
| t <sub>OH</sub>                   | Output Hold from Address, $\overline{CE}$ or $\overline{OE}$ , Whichever Occurred First |  | 0             |     | ns    |

# **10. AC Waveforms for Read Operation**<sup>(1)</sup>



Notes: 1. Timing measurement references are 0.8V and 2.0V. Input AC drive levels are 0.45V and 2.4V, unless otherwise specified.

- 2.  $\overline{OE}$  may be delayed up to t<sub>CE</sub> t<sub>OE</sub> after the falling edge of  $\overline{CE}$  without impact on t<sub>CE</sub>.
- 3.  $\overline{OE}$  may be delayed up to  $t_{ACC}$   $t_{OE}$  after the address is valid without impact on  $t_{ACC}$ .

http://www.BDTIC.com/ATI

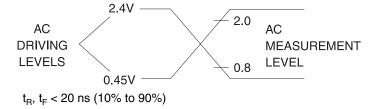
- 4. This parameter is only sampled and is not 100% tested.
- 5. Output float is defined as the point when data is no longer driven.



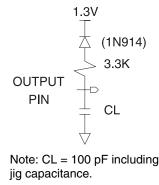
AT27LV010A

# AT27LV010A

#### **11. Input Test Waveforms and Measurement Level**



### 12. Output Test Load



# 13. Pin Capacitance

 $f = 1 \text{ MHz}, T = 25^{\circ}C^{(1)}$ 

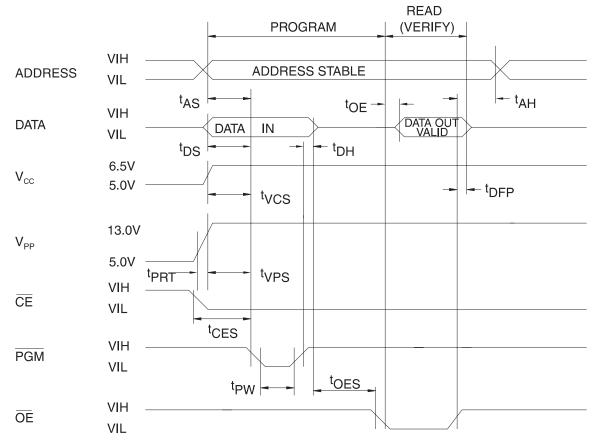
| Symbol           | Тур | Мах | Units | Conditions     |
|------------------|-----|-----|-------|----------------|
| C <sub>IN</sub>  | 4   | 8   | pF    | $V_{IN} = 0V$  |
| C <sub>OUT</sub> | 8   | 12  | pF    | $V_{OUT} = 0V$ |

Note: 1. Typical values for nominal supply voltage. This parameter is only sampled and is not 100% tested.





# 14. Programming Waveforms<sup>(1)</sup>



- Notes: 1. The Input Timing Reference is 0.8V for  $\rm V_{IL}$  and 2.0V for  $\rm V_{IH}.$ 
  - 2.  $t_{OE}$  and  $t_{DFP}$  are characteristics of the device but must be accommodated by the programmer.

http://www.BDTIC.com/A7

 When programming the AT27LV010A a 0.1 μF capacitor is required across V<sub>PP</sub> and ground to suppress spurious voltage transients.

AT27LV010A

8

# **15. DC Programming Characteristics**

 $T_A = 25 \pm 5^{\circ}C, V_{CC} = 6.5 \pm 0.25V, V_{PP} = 13.0 \pm 0.25V$ 

| Symbol           |   |   | Lir  |                       |       |
|------------------|---|---|------|-----------------------|-------|
|                  | Parameter   | Test Conditions                           |      | Мах                   | Units |
| I <sub>LI</sub>  | Input Load Current                                  | $V_{IN} = V_{IL}, V_{IH}$                 |      | ±10                   | μA    |
| V <sub>IL</sub>  | Input Low Level                                     |   | -0.6 | 0.8                   | V     |
| V <sub>IH</sub>  | Input High Level                                    |   | 2.0  | V <sub>cc</sub> + 0.5 | V     |
| V <sub>OL</sub>  | Output Low Voltage                                  | I <sub>OL</sub> = 2.1 mA                  |      | 0.4                   | V     |
| V <sub>OH</sub>  | Output High Voltage                                 | I <sub>OH</sub> = -400 μA                 | 2.4  |                       | V     |
| I <sub>CC2</sub> | V <sub>CC</sub> Supply Current (Program and Verify) |   |      | 40                    | mA    |
| I <sub>PP2</sub> | V <sub>PP</sub> Supply Current                      | $\overline{CE} = \overline{PGM} = V_{IL}$ |      | 20                    | mA    |
| V <sub>ID</sub>  | A9 Product Identification Voltage                   |   | 11.5 | 12.5                  | V     |

# **16. AC Programming Characteristics**

 $T_{A} = 25 \pm 5^{\circ}C, \ V_{CC} = 6.5 \pm 0.25V, \ V_{PP} = 13.0 \pm 0.2V$ 

|                  |   |   | Lir |     |       |
|------------------|---|---|-----|-----|-------|
| Symbol           | Parameter   | Test Conditions <sup>(1)</sup>                | Min | Max | Units |
| t <sub>AS</sub>  | Address Setup Time                                    |   | 2   |     | μs    |
| t <sub>CES</sub> | CE Setup Time   |   | 2   |     | μs    |
| t <sub>OES</sub> | OE Setup Time   | Input Rise and Fall Times:                    | 2   |     | μs    |
| t <sub>DS</sub>  | Data Setup Time                                       | (10% to 90%) 20 ns                            | 2   |     | μs    |
| t <sub>AH</sub>  | Address Hold Time                                     | Input Pulse Levels:                           | 0   |     | μs    |
| t <sub>DH</sub>  | Data Hold Time  | 0.45V to 2.4V                                 | 2   |     | μs    |
| t <sub>DFP</sub> | OE High to Output Float Delay <sup>(2)</sup>          |   | 0   | 130 | ns    |
| t <sub>VPS</sub> | V <sub>PP</sub> Setup Time                            | Input Timing Reference Level:<br>0.8V to 2.0V | 2   |     | μs    |
| t <sub>VCS</sub> | V <sub>CC</sub> Setup Time                            | 0.00 10 2.00                                  | 2   |     | μs    |
| t <sub>PW</sub>  | PGM Program Pulse Width <sup>(3)</sup>                | Output Timing Reference Level:                | 95  | 105 | μs    |
| t <sub>OE</sub>  | Data Valid from OE                                    | 0.8V to 2.0V                                  |     | 150 | ns    |
| t <sub>PRT</sub> | V <sub>PP</sub> Pulse Rise Time During<br>Programming |   | 50  |     | ns    |

Notes: 1. V<sub>CC</sub> must be applied simultaneously or before V<sub>PP</sub> and removed simultaneously or after V<sub>PP</sub>

 This parameter is only sampled and is not 100% tested. Output Float is defined as the point where data is no longer driven – see timing diagram.

3. Program Pulse width tolerance is 100  $\,\mu\text{sec}\pm5\%.$ 

)://www.]

# 17. Atmel's AT27LV010A Integrated Product Identification Code<sup>(1)</sup>

|              |            | Pins |            |            |    |    |    | Hex |    |      |
|--------------|------------|------|------------|------------|----|----|----|-----|----|------|
| Codes        | <b>A</b> 0 | 07   | <b>O</b> 6 | <b>O</b> 5 | 04 | O3 | 02 | 01  | 00 | Data |
| Manufacturer | 0          | 0    | 0          | 0          | 1  | 1  | 1  | 1   | 0  | 1E   |
| Device Type  | 1          | 0    | 0          | 0          | 0  | 0  | 1  | 0   | 1  | 05   |

Note: 1. The AT27LV010A has the same Product Identification Code as the AT27C010. Both are programming compatible.

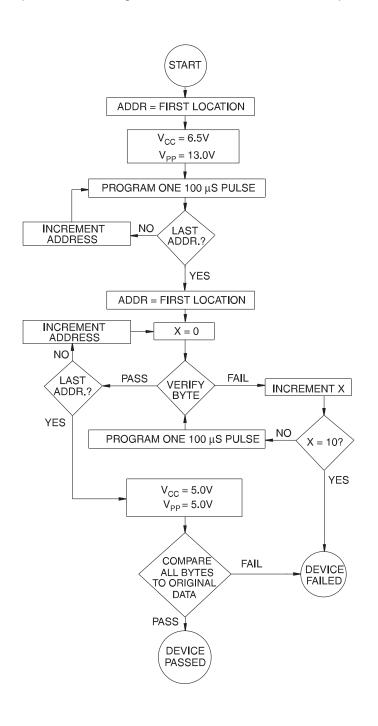


DTIC.com/ATMEL



### 18. Rapid Programming Algorithm

A 100  $\mu$ s PGM pulse width is used to program. The address is set to the first location. V<sub>CC</sub> is raised to 6.5V and V<sub>PP</sub> is raised to 13.0V. Each address is first programmed with one 100  $\mu$ s PGM pulse without verification. Then a verification/reprogramming loop is executed for each address. In the event a byte fails to pass verification, up to 10 successive 100  $\mu$ s pulses are applied with a verification after each pulse. If the byte fails to verify after 10 pulses have been applied, the part is considered failed. After the byte verifies properly, the next address is selected until all have been checked. V<sub>PP</sub> is then lowered to 5.0V and V<sub>CC</sub> to 5.0V. All bytes are read again and compared with the original data to determine if the device passes or fails.



10 AT27LV010A

http://www.BDTIC.com/A7

### **19. Ordering Information**

#### 19.1 Standard Package

| t <sub>ACC</sub> | I <sub>CC</sub> (mA)   V <sub>CC</sub> = 3.6V   Active Standby |      |                              |                    |                 |
|------------------|--|------|------------------------------|--------------------|-----------------|
| (ns)             |  |      | Active Standby Ordering Code |                    | Package         |
| 70               | 8  | 0.02 | AT27LV010A-70JI              | 32J                | Industrial      |
|                  |  |      | AT27LV010A-70TI              | 32T                | (-40°C to 85°C) |
|                  |  |      | AT27LV010A-70VI              | 32V <sup>(1)</sup> |                 |

Note:

Not recommended for new designs. Use Green package option.

#### 19.2 Green Package Option (Pb/Halide-free)

| t <sub>ACC</sub> | I <sub>CC</sub> (mA)   V <sub>CC</sub> = 3.6V   Active Standby |      |                           |     |                 |
|------------------|--|------|---------------------------|-----|-----------------|
| (ns)             |  |      | ive Standby Ordering Code |     | Operation Range |
| 70               | 8  | 0.02 | AT27LV010A-70JU           | 32J | Industrial      |
|                  |  |      | AT27LV010A-70TU           | 32T | (-40°C to 85°C) |

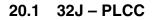
Note: 1. The 32-lead VSOP package is not recommended for new designs.

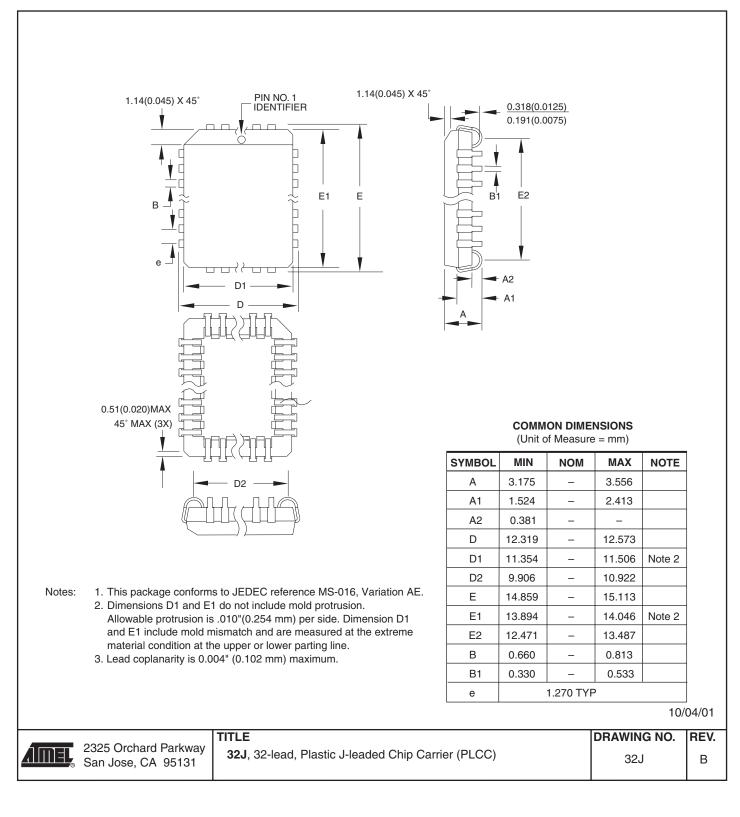
| Package Type |  |
|--------------|--|
| 32J          | 32-lead, Plastic J-leaded Chip Carrier (PLCC)      |
| 32T          | 32-lead, Plastic Thin Small Outline Package (TSOP) |
| 32V          | 32-lead, Plastic Thin Small Outline Package (VSOP) |

0548E-EPROM-12/07 http://www.BDTIC.com/ATMEL



# 20. Packaging Information



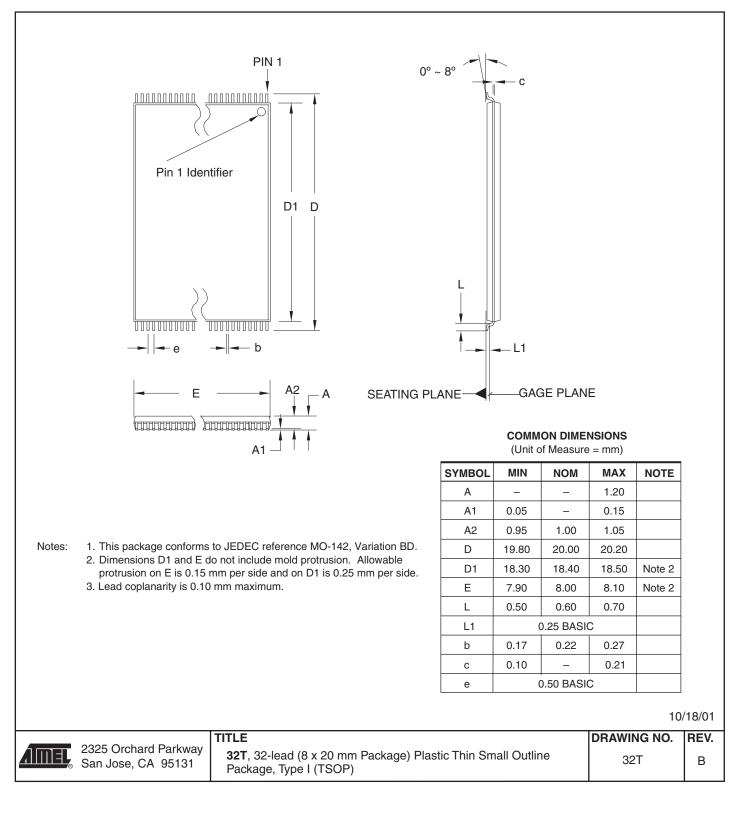


http://www.BDTIC.com/A'

12 AT27LV010A

# AT27LV010A

#### 20.2 32T – TSOP



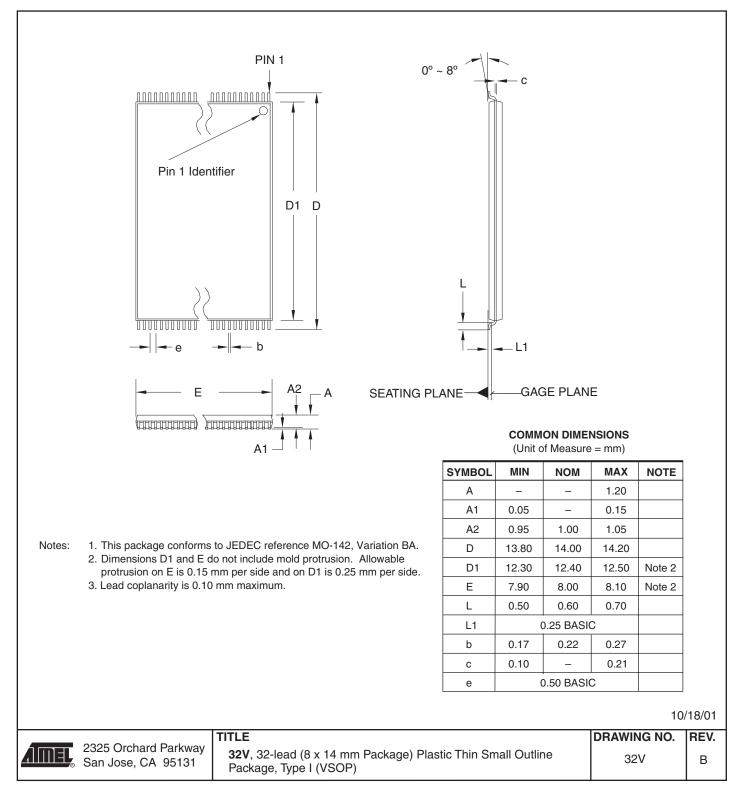
**DTIC.com/ATM** 

0548E-EPROM-12/07

**b://www.** 



#### 20.3 32V – VSOP



http://www.BDTIC.com/A7

14 AT27LV010A