



SLLS983C -JUNE 2009-REVISED JULY 2010

# ISOLATED CAN TRANSCEIVER

Check for Samples: ISO1050

#### **FEATURES**

- 5000-V<sub>RMS</sub> Isolation (DW Package)
- 2500-V<sub>RMS</sub> Isolation (DUB Package)
- **Failsafe Outputs**
- Low Loop Delay: 150 ns Typical
- 50 kV/μs Typical Transient Immunity
- Meets or Exceeds ISO 11898 requirements
- Bus-Fault Protection of -27 V to 40 V
- **Dominant Time-Out Function**
- IEC 60747-5-2 (VDE 0884, Rev. 2) & IEC 61010-1 Approved
- **UL 1577, IEC 60950-1 and CSA Approvals Pending**
- 3.3-V Inputs are 5-V Tolerant

Typical 25-Year Life at Rated Working Voltage (see Application Report SLLA197 and Figure 15)

#### **APPLICATIONS**

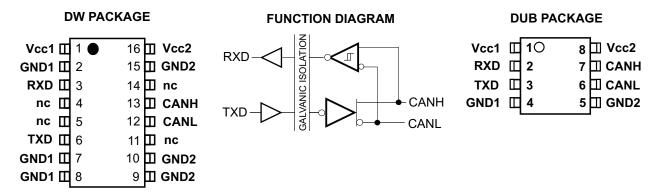
- CAN Data Buses
- **Industrial Automation** 
  - **DeviceNet Data Buses**
  - CANopen Data Buses
  - CANKingdom Data Buses
- **Medical Scanning and Imaging**
- **Security Systems**
- **Telecom Base Station Status and Control**
- **Building Automation**

#### DESCRIPTION

The ISO1050 is a galvanically isolated CAN transceiver that meets or exceeds the specifications of the ISO 11898 standard. The device has the logic input and output buffers separated by a silicon oxide (SiO<sub>2</sub>) insulation barrier that provides galvanic isolation of up to 5000 V<sub>RMS</sub> for DW Package and 2500 V<sub>RMS</sub> for DUB package. Used in conjunction with isolated power supplies, the device prevents noise currents on a data bus or other circuits from entering the local ground and interfering with or damaging sensitive circuitry.

As a CAN transceiver, the device provides differential transmit capability to the bus and differential receive capability to a CAN controller at signaling rates up to 1 megabit per second (Mbps). Designed for operation in especially harsh environments, the device features cross-wire, overvoltage and loss of ground protection from -27 V to 40 V and over-temperature shut-down, as well as −12 V to 12 V common-mode range.

The ISO1050 is characterized for operation over the ambient temperature range of -55°C to 105°C.



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These devices have limited built-in ESD protection. The leads should be shorted together or the device placed in conductive foam during storage or handling to prevent electrostatic damage to the MOS gates.

# ABSOLUTE MAXIMUM RATINGS(1) (2)

		·		VALUE / UNIT		
V <sub>CC1</sub> , V <sub>CC2</sub>	Supply voltage (3)			-0.5 V to 6 V		
V <sub>I</sub>	Voltage input (TXD)			-0.5 V to 6 V		
V <sub>CANH</sub> or V <sub>CANH</sub>	Voltage range at any bus	Voltage range at any bus terminal (CANH, CANL)				
lo	Receiver output current		±15 mA			
	Human Body Model	JEDEC Standard 22, Method A114-C.01	Bus pins and GND2 <sup>(4)</sup>	±4 kV		
ESD			All pins	±4 kV		
	Charged Device Model	JEDEC Standard 22, Test Method C101	All pins	±1.5 kV		
	Machine Model	ANSI/ESDS5.2-1996	All pins	±200 V		
T <sub>stg</sub>	Storage temperature			–65°C to 150°C		
T <sub>J</sub>	Junction temperature			-55°C to 150°C		

- (1) Stresses beyond those listed under absolute maximum ratings may cause permanent damage to the device. These are stress ratings only and functional operation of the device at these or any other conditions beyond those indicated under recommended operating conditions is not implied. Exposure to absolute-maximum-rated conditions for extended periods may affect device reliability.
- (2) This isolator is suitable for basic isolation within the safety limiting data. Maintenance of the safety data must be ensured by means of protective circuitry.
- (3) All input and output logic voltage values are measured with respect to the GND1 logic side ground. Differential bus-side voltages are measured to the respective bus-side GND2 ground terminal.
- (4) Tested while connected between Vcc2 and GND2.

#### RECOMMENDED OPERATING CONDITIONS

			MIN	NOM	MAX	UNIT
V <sub>CC1</sub>	Supply voltage, controller sign	de	3		5.5	V
V <sub>CC2</sub>	Supply voltage, bus side		4.75	5	5.25	V
V <sub>I</sub> or V <sub>IC</sub>	Voltage at bus pins (separat	oltage at bus pins (separately or common mode)			12	V
V <sub>IH</sub>	High-level input voltage	TXD	2		5.25	V
V <sub>IL</sub>	Low-level input voltage	TXD	0		0.8	V
$V_{ID}$	Differential input voltage		-7		7	V
		Driver	-70			mA
I <sub>OH</sub>	High-level output current	Receiver	-4			
	Law law law and a compact	Driver			70	1
I <sub>OL</sub>	Low-level output current	ow-level output current Receiver			4	mA
T <sub>A</sub>	Ambient Temperature		-55		105	°C
TJ	Junction temperature (see T	unction temperature (see THERMAL CHARACTERISTICS)			125	°C

<sup>(1)</sup> The algebraic convention, in which the least positive (most negative) limit is designated as minimum is used in this data sheet.

# **SUPPLY CURRENT**

over recommended operating conditions (unless otherwise noted)

PARAMETER		TEST CONDITIONS	MIN TYP <sup>(1)</sup>	MAX	UNIT	
L V Cupply gurrent			$V_I = 0 \text{ V or } V_{CC1}$ , $V_{CC1} = 3.3 \text{V}$	1	2	A
ICC1	V <sub>CC1</sub> Supply current		$V_I = 0 \text{ V or } V_{CC1}$ , $V_{CC1} = 5V$	2	3	mA
l V Complete and the		Dominant	$V_I = 0 V$ , $60-\Omega$ Load	52	73	A
ICC2	V <sub>CC2</sub> Supply current	Recessive	$V_I = V_{CC1}$	8	12	mA

(1) All typical values are at 25°C with  $V_{CC1} = V_{CC2} = 5V$ .



#### **DEVICE SWITCHING CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>loop1</sub>	Total loop delay, driver input to receiver output, Recessive to Dominant	See Figure 9	112	150	210	ns
t <sub>loop2</sub>	Total loop delay, driver input to receiver output, Dominant to Recessive	See Figure 9	112	150	210	ns

#### **DRIVER ELECTRICAL CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT	
\ /	Due sutant valtage (Descipent)	CANH	Can Figure 4 and Figure 2 V 2 V B COO	2.9	3.5	4.5	V	
$V_{O(D)}$	Bus output voltage (Dominant)	CANL	See Figure 1 and Figure 2, $V_I = 0 \text{ V}$ , $R_L = 60\Omega$	0.8	1.2	1.5	V	
V <sub>O(R)</sub>	Bus output voltage (Recessive)		See Figure 1 and Figure 2, $V_I = 2 V$ , $R_L = 60 \Omega$	2	2.3	3	V	
V	Differential output voltage (Dominant)		See Figure 1, Figure 2 and Figure 3, $V_I$ = 0 $V$ , $R_L$ = $60\Omega$	1.5		3		
$V_{OD(D)}$			See Figure 1, Figure 2, and Figure 3 $V_I = 0 V$ , $R_L = 45\Omega$ , $Vcc > 4.8V$			3	V	
.,	D(R) Differential output voltage (Recessive)		See Figure 1 and Figure 2, $V_I = 3 V$ , $R_L = 60 \Omega$	-0.12		0.012		
$V_{OD(R)}$			V <sub>I</sub> = 3 V, No Load	-0.5		0.05	V	
V <sub>OC(D)</sub>	Common-mode output voltage (Dom	inant)	See Figure 0	2	2.3	3	V	
V <sub>OC(pp)</sub>	Peak-to-peak common-mode output	voltage	See Figure 8		0.3		V	
I <sub>IH</sub>	High-level input current, TXD input		V <sub>I</sub> at 2 V			5	μΑ	
I <sub>IL</sub>	Low-level input current, TXD input		V <sub>I</sub> at 0.8 V	-5			μΑ	
I <sub>O(off)</sub>	Power-off TXD leakage current		V <sub>CC1</sub> , V <sub>CC2</sub> at 0 V, TXD at 5 V			10	μΑ	
			See Figure 11, V <sub>CANH</sub> = -12 V, CANL Open	-105	-72			
	Chart aireuit ataadu atata autaut aur	ont	See Figure 11, V <sub>CANH</sub> = 12 V, CANL Open		0.36	1	A	
I <sub>OS(ss)</sub>	Short-circuit steady-state output curr	ent	See Figure 11, V <sub>CANL</sub> =–12 V, CANH Open	-1	-0.5		mA	
			See Figure 11, V <sub>CANL</sub> = 12 V, CANH Open		71	105		
Co	Output capacitance		See receiver input capacitance					
CMTI	Common-mode transient immunity		See Figure 13, V <sub>I</sub> = V <sub>CC</sub> or 0 V	25	50		kV/μs	

#### **DRIVER SWITCHING CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>PLH</sub>	Propagation delay time, recessive-to-dominant output		31	74	110	
t <sub>PHL</sub>	Propagation delay time, dominant-to-recessive output	One Figure 4	25	44	75	
t <sub>r</sub>	Differential output signal rise time	See Figure 4		20	50	ns
t <sub>f</sub>	Differential output signal fall time			20	50	
t <sub>dom</sub>	Dominant time-out	↓ C <sub>L</sub> =100 pF, See Figure 10	300	450	700	μS



#### RECEIVER ELECTRICAL CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP <sup>(1)</sup>	MAX	UNIT
V <sub>IT+</sub>	Positive-going bus input threshold voltage	See Table 1		750	900	mV
$V_{\text{IT-}}$	Negative-going bus input threshold voltage	See Table 1	500	650		mV
V <sub>hys</sub>	Hysteresis voltage (V <sub>IT+</sub> – V <sub>IT-</sub> )			150		mV
V	Lligh level output voltage with Voc. 5V	I <sub>OH</sub> = -4 mA, See Figure 6	$V_{CC} - 0.8$	4.6		V
V <sub>OH</sub>	High-level output voltage with Vcc = 5V	$I_{OH} = -20 \mu A$ , See Figure 6	V <sub>CC</sub> - 0.1	5		V
V	High-level output voltage with Vcc1 = 3.3V	I <sub>OL</sub> = 4 mA, See Figure 6	$V_{CC} - 0.8$	3.1		V
V <sub>OH</sub>		I <sub>OL</sub> = 20 μA, See Figure 6	V <sub>CC</sub> - 0.1	3.3		V
V	Law lawal and and walks are	I <sub>OL</sub> = 4 mA, See Figure 6		0.2	0.4	V
V <sub>OL</sub>	Low-level output voltage	I <sub>OL</sub> = 20 μA, See Figure 6		0	0.1	V
Cı	Input capacitance to ground, (CANH or CANL)	TXD at 3 V, $V_I = 0.4 \sin (4E6\pi t) + 2.5V$		6		pF
C <sub>ID</sub>	Differential input capacitance	TXD at 3 V, $V_I = 0.4 \sin (4E6\pi t)$		3		pF
R <sub>ID</sub>	Differential input resistance	TXD at 3 V	30		80	kΩ
R <sub>IN</sub>	Input resistance (CANH or CANL)	TXD at 3 V	15	30	40	kΩ
R <sub>I(m)</sub>	Input resistance matching (1 – [R <sub>IN (CANL)</sub> ] / R <sub>IN (CANL)</sub> ]) × 100%	$V_{CANH} = V_{CANL}$	-3%	0%	3%	
CMTI	Common-mode transient immunity	V <sub>I</sub> = V <sub>CC</sub> or 0 V, See Figure 13	25	50		kV/μs

<sup>(1)</sup> All typical values are at 25°C with  $V_{CC1} = V_{CC2} = 5V$ .

#### RECEIVER SWITCHING CHARACTERISTICS

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
t <sub>PLH</sub>	Propagation delay time, low-to-high-level output		66	90	130	
t <sub>PHL</sub>	Propagation delay time, high-to-low-level output	TXD at 3 V, See Figure 6	51	80	105	
t <sub>r</sub>	Output signal rise time	TXD at 3 V, See Figure 6		3	6	ns
t <sub>f</sub>	Output signal fall time			3	6	
t <sub>fs</sub>	Failsafe output delay time from bus-side power loss	VCC1 at 5 V, See Figure 12		6		μS



#### PARAMETER MEASUREMENT INFORMATION

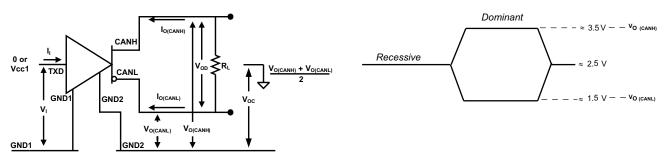


Figure 1. Driver Voltage, Current and Test Definitions

Figure 2. Bus Logic State Voltage Definitions

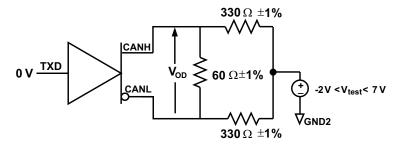
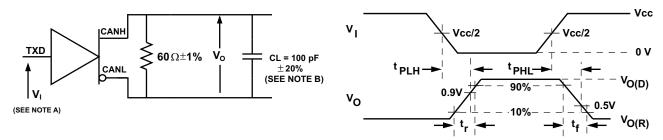


Figure 3. Driver V<sub>OD</sub> with Common-mode Loading Test Circuit



- A. The input pulse is supplied by a generator having the following characteristics: PRR  $\leq$  125 kHz, 50% duty cycle,  $t_f \leq$  6 ns,  $t_f \leq$  6 ns,  $t_G \leq$  50 $\Omega$ .
- B. C<sub>L</sub> includes instrumentation and fixture capacitance within ±20%.

Figure 4. Driver Test Circuit and Voltage Waveforms

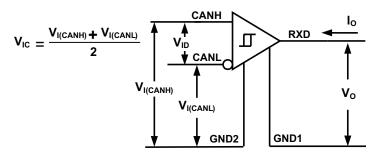
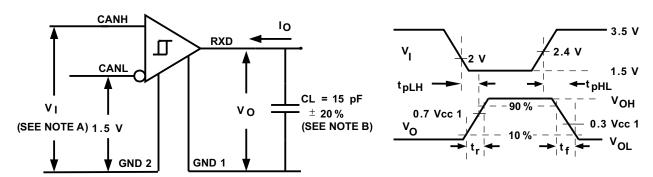


Figure 5. Receiver Voltage and Current Definitions



# PARAMETER MEASUREMENT INFORMATION (continued)

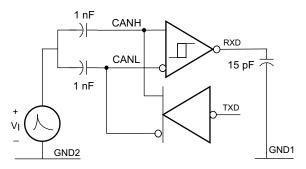


- A. The input pulse is supplied by a generator having the following characteristics: PRR  $\leq$  125 kHz, 50% duty cycle,  $t_r \leq$  6 ns,  $t_f \leq$  6 ns,  $t_O = 50\Omega$ .
- B. C<sub>1</sub> includes instrumentation and fixture capacitance within ±20%.

Figure 6. Receiver Test Circuit and Voltage Waveforms

**Table 1. Differential Input Voltage Threshold Test** 

	INPUT				
V <sub>CANH</sub>	V <sub>CANL</sub>	V <sub>ID</sub>		R	
–11.1 V	-12 V	900 mV	L		
12 V	11.1 V	900 mV	L	.,	
-6 V	-12 V	6 V	L	V <sub>OL</sub>	
12 V	6 V	6 V	L		
–11.5 V	-12 V	500 mV	Н		
12 V	11.5 V	500 mV	Н		
-12 V	-6 V	-6 V	Н	V <sub>OH</sub>	
6 V	12 V	-6 V	Н		
Open	Open	X	Н		



The waveforms of the applied transients are in accordance with ISO 7637 part 1, test pulses 1, 2, 3a, and 3b.

Figure 7. Transient Over-Voltage Test Circuit



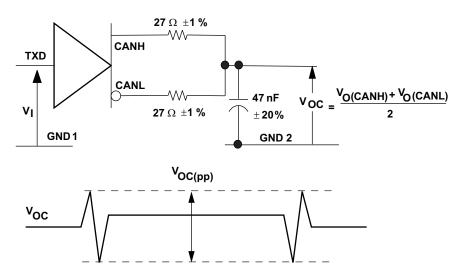


Figure 8. Peak-to-Peak Output Voltage Test Circuit and Waveform

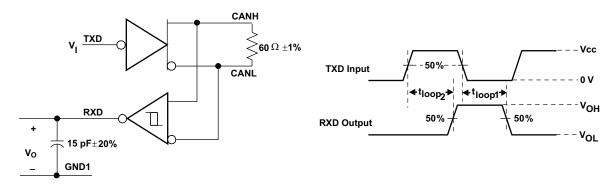
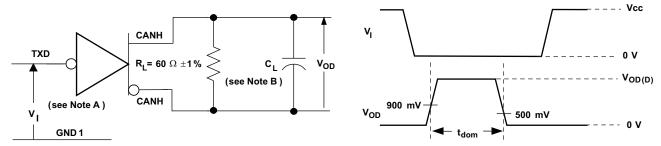


Figure 9. t<sub>LOOP</sub> Test Circuit and Voltage Waveforms



- A. The input pulse is supplied by a generator having the following characteristics: PRR  $\leq$  125 kHz, 50% duty cycle,  $t_r \leq$  6 ns,  $t_f \leq$  6 ns,  $Z_O = 50\Omega$ .
- B. C<sub>L</sub> includes instrumentation and fixture capacitance within ±20%.

Figure 10. Dominant Timeout Test Circuit and Voltage Waveforms



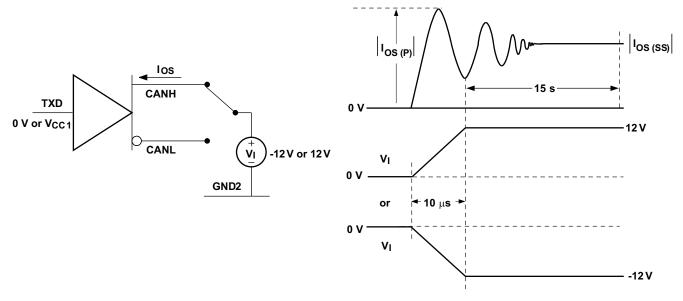


Figure 11. Driver Short-Circuit Current Test Circuit and Waveforms

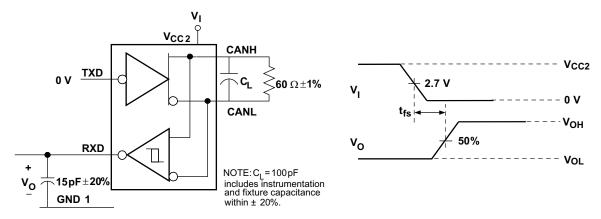


Figure 12. Failsafe Delay Time Test Circuit and Voltage Waveforms



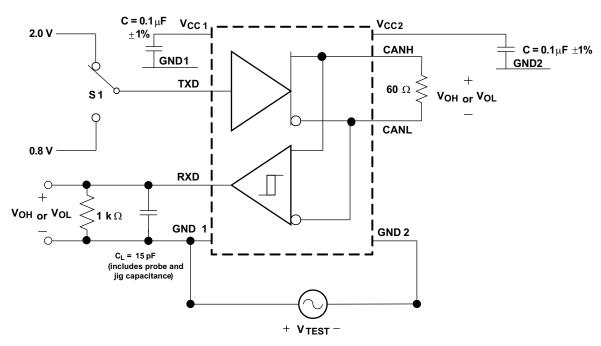


Figure 13. Common-Mode Transient Immunity Test Circuit

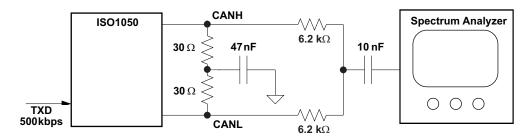


Figure 14. Electromagnetic Emissions Measurement Setup

#### **DEVICE INFORMATION**

# **FUNCTION TABLE**(1)

		DRIVER				RECEIVER	
INPUTS	IPUTS OUTPUTS		DUC STATE	BUS STATE	DIFFERENTIAL INPUTS	OUTPUT	BUS STATE
TXD	CANH	CANL	BUSSIAIE		V <sub>ID</sub> = CANH-CANL	RXD	BUS STATE
L <sup>(2)</sup>	Н	L	DOMINANT		V <sub>ID</sub> ≥ 0.9 V	L	DOMINANT
Н	Z	Z	RECESSIVE		$0.5 \text{ V} < \text{V}_{\text{ID}} < 0.9 \text{ V}$	?	?
Open	Z	Z	RECESSIVE		V <sub>ID</sub> ≤ 0.5 V	Н	RECESSIVE
Х	Z	Z	RECESSIVE		Open	Н	RECESSIVE

- (1) H = high level; L = low level; X = irrelevant; ? = indeterminate; Z = high impedance
- (2) Logic low pulses to prevent dominant time-out.



# ISOLATOR CHARACTERISTICS (1) (2)

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS		MIN	TYP	MAX	UNIT
L(I01)	Minimum air gap (Clearance)	Shortest terminal to terminal distance through air		6.1			mm
L(102)	Minimum external tracking (Creepage)	Shortest terminal to terminal distance across the package surface	DUB-8	6.8			mm
L(I01)	Minimum air gap (Clearance)	Shortest terminal to terminal distance through air		8.34			mm
L(102)	Minimum external tracking (Creepage)	Shortest terminal to terminal distance across the package surface	DW-16	8.10			mm
	Minimum Internal Gap (Internal Clearance)	Distance through the insulation		0.014			mm
R <sub>IO</sub>	Isolation resistance	Input to output, $V_{IO}$ = 500 V, all pins on each side o barrier tied together creating a two-terminal device, 100°C			>10 <sup>12</sup>		Ω
		Input to output V <sub>IO</sub> = 500 V, 100°C ≤Tamb <≤Tamb max			>10 <sup>11</sup>		Ω
C <sub>IO</sub>	Barrier capacitance	$V_1 = 0.4 \sin (4E6\pi t)$			1.9		pF
Cı	Input capacitance to ground	$V_1 = 0.4 \sin (4E6\pi t)$			1.3		pF

<sup>(1)</sup> Creepage and clearance requirements should be applied according to the specific equipment isolation standards of an application. Care should be taken to maintain the creepage and clearance distance of a board design to ensure that the mounting pads of the isolator on the printed circuit board do not reduce this distance.

#### **INSULATION CHARACTERISTICS**

over recommended operating conditions (unless otherwise noted)

	PARAMETE	≣R	TEST CONDITIONS	SPECIFICATION	UNIT
.,	Maximum working insulation	8-DUB Package		560	\/= = = l-
$V_{IORM}$	voltage per IEC	16-DW Package		1200	Vpeak
		8-DUB Package	V <sub>PR</sub> = 1.875 x V <sub>IORM</sub> , t = 1	1050	
$V_{PR}$	Input to output test voltage per IEC	16-DW Package	sec (100% production) Partial discharge < 5 pC	2250	Vpeak
V	Transient overvoltage per IEC		t = 60 sec (qualification)	4000	\/nools
V <sub>IOTM</sub>			t = 1 sec (100% production)	4000	Vpeak
		8-DUB Package	t = 60 sec (qualification)	2500	\/
.,	loolation valtage man I II		t = 1 sec (100% production)	3000	Vrms
V <sub>ISO</sub>	Isolation voltage per UL	AC DW Dankers	t = 60 sec (qualification)	5000	
		16-DW Package	t = 1 sec (100% production)	6000	Vrms
R <sub>S</sub>	Isolation voltage per UL		V <sub>IO</sub> = 500 V at T <sub>S</sub>	> 10 <sup>9</sup>	Ω
	Pollution Degree			2	

#### **IEC 60664-1 RATINGS**

PARAMETER	TEST CONDITIONS	SPECIFICATION
Basic isolation group	Material group	III-a
	Rated mains voltage ≤ 150 Vrms	I–IV
Installation classification	Rated mains voltage ≤ 300 Vrms	<b>III</b>
	Rated mains voltage ≤ 400 Vrms	I–II

<sup>(2)</sup> Creepage and clearance on a printed circuit board become equal according to the measurement techniques shown in the Isolation Glossary. Techniques such as inserting grooves and/or ribs on a printed circuit board are used to help increase these specifications.



#### **IEC SAFETY LIMITING VALUES**

safety limiting intends to prevent potential damage to the isolation barrier upon failure of input or output circuitry. A failure of the IO can allow low resistance to ground or the supply and, without current limiting dissipate sufficient power to overheat the die and damage the isolation barrier potentially leading to secondary system failures.

	PARAMETER		TEST CONDITIONS	MIN	TYP	MAX	UNIT
		DUD	$\theta_{JA} = 73.3 \text{ °C/W}, V_I = 5.5 \text{ V}, T_J = 150 \text{°C}, T_A = 25 \text{°C}$			310	A
	Cofety input output or output ourrent	DUB-8	$\theta_{JA} = 73.3 \text{ °C/W}, V_I = 3.6 \text{ V}, T_J = 150 \text{°C}, T_A = 25 \text{°C}$			474	mA
IS	Safety input, output, or supply current	DW-16	$\theta_{JA} = 76 \text{ °C/W}, V_I = 5.5 \text{ V}, T_J = 150 \text{ °C}, T_A = 25 \text{ °C}$			299	
			$\theta_{JA} = 76 \text{ °C/W}, V_I = 3.6 \text{ V}, T_J = 150 \text{ °C}, T_A = 25 \text{ °C}$			457	mA
T <sub>S</sub>	Maximum case temperature					150	°C

The safety-limiting constraint is the absolute maximum junction temperature specified in the absolute maximum ratings table. The power dissipation and junction-to-air thermal impedance of the device installed in the application hardware determines the junction temperature. The assured junction-to-air thermal resistance in the Thermal Characteristics table is that of a device installed on a High-K Test Board for Leaded Surface Mount Packages. The power is the recommended maximum input voltage times the current. The junction temperature is then the ambient temperature plus the power times the junction-to-air thermal resistance.

#### REGULATORY INFORMATION

VDE	CSA	UL
Certified according to IEC 60747-5-2	Approved under CSA Component Acceptance Notice	Recognized under 1577 Component Recognition Program <sup>(1)</sup>
File Number: 40016131	File Number: pending	File Number: pending

<sup>(1)</sup> Production tested ≥ 3000 VRMS for 1 second in accordance with UL 1577.

#### THERMAL INFORMATION (DUB-8 PACKAGE)

over recommended operating conditions (unless otherwise noted)

	PARAMETER	TEST CONDITIONS	MIN	TYP	MAX	UNIT
0	lunation to air	Low-K Thermal Resistance <sup>(1)</sup>		120		°C/W
$\theta_{JA}$	Junction-to-air	High-K Thermal Resistance		73.3		°C/W
$\theta_{JB}$	Junction-to-board thermal resistance	Low-K Thermal Resistance		10.2		°C/W
$\theta_{\text{JC}}$	Junction-to-case thermal resistance	Low-K Thermal Resistance		14.5		°C/W
P <sub>D</sub>	Device power dissipation	$V_{\rm CC1}$ =5.5V, $V_{\rm CC2}$ =5.25V, $T_{\rm A}$ =105°C, $R_{\rm L}$ = 60 $\Omega$ , TXD input is a 500kHz 50% duty-cycle square wave			200	mW
T <sub>j shutdown</sub>	Thermal shutdown temperature (2)			190		ů

<sup>(1)</sup> Tested in accordance with the Low-K or High-K thermal metric definitions of EIA/JESD51-3 for leaded surface mount packages.

#### THERMAL INFORMATION (DW-16 PACKAGE)

		ISO1050		
	THERMAL METRIC <sup>(1)</sup>	DW	UNITS	
		16		
$\theta_{JA}$	Junction-to-ambient thermal resistance	76.0		
θ <sub>JCtop</sub>	Junction-to-case (top) thermal resistance	41		
ЭЈВ	Junction-to-board thermal resistance	47.7	9000	
₽JT	Junction-to-top characterization parameter	14.4	°C/W	
<b>∤</b> ЈВ	Junction-to-board characterization parameter	38.2		
JCbot	Junction-to-case (bottom) thermal resistance	n/a		

<sup>(1)</sup> For more information about traditional and new thermal metrics, see the IC Package Thermal Metrics application report, SPRA953.

<sup>(2)</sup> Extended operation in thermal shutdown may affect device reliability.



# LIFE EXPECTANCY vs WORKING VOLTAGE (8-DUB PACKAGE)

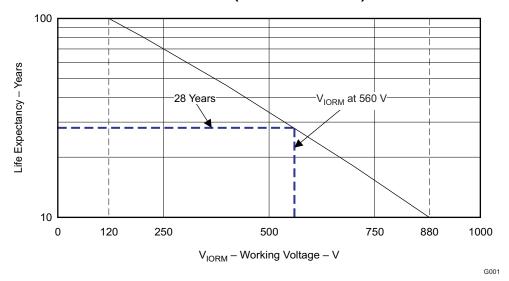
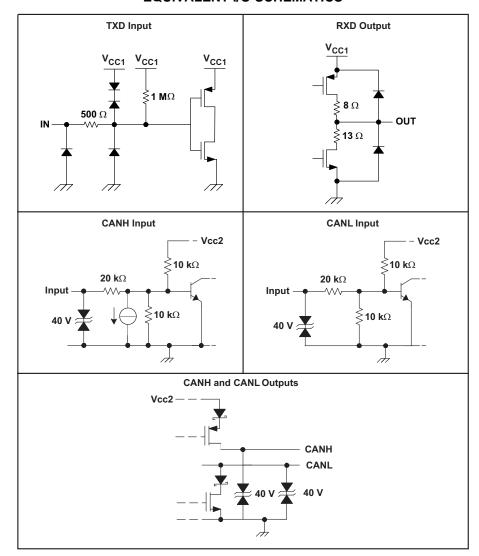


Figure 15. Life Expectancy vs Working Voltage



#### **EQUIVALENT I/O SCHEMATICS**



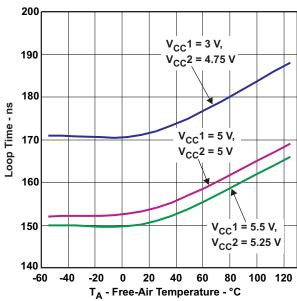


#### TYPICAL CHARACTERISTICS

#### **RECESSIVE-TO-DOMINANT LOOP TIME**

VS

FREE-AIR TEMPERATURE (across Vcc)



# Figure 16. SUPPLY CURRENT (RMS)

vs

SIGNALING RATE (kbps)

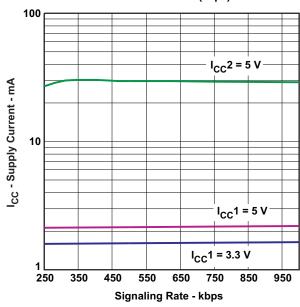


Figure 18.

#### DOMINANT-TO-RECESSIVE LOOP TIME

vs

FREE-AIR TEMPERATURE (across Vcc)

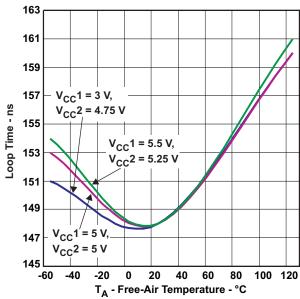


Figure 17.

#### DRIVER OUTPUT VOLTAGE

vs

FREE-AIR TEMPERATURE

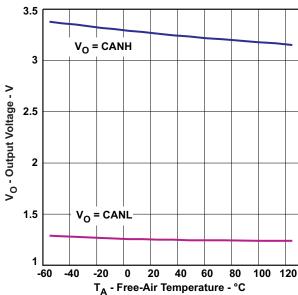
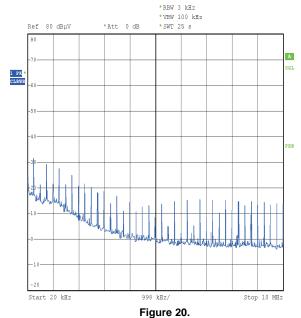


Figure 19.



# **TYPICAL CHARACTERISTICS (continued)**

#### **EMISSIONS SPECTRUM TO 10 MHz**



# EMISSIONS SPECTRUM TO 50 MHz

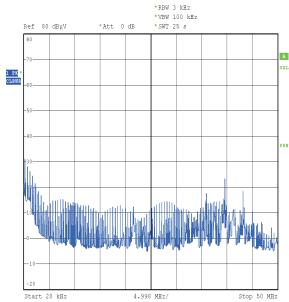


Figure 21.



#### **APPLICATION INFORMATION**

#### DOMINANT TIME-OUT

A dominant time-out circuit in the ISO1050 prevents the driver from blocking network communications if a local controller fault occurs. The time-out circuit is triggered by a falling edge on TXD. If no rising edge occurs on TXD before the time-out of the circuits expires, the driver is disabled to prevent the local node from continuously transmitting a Dominant bit. If a rising edge occurs on TXD, commanding a Recessive bit, the timer will be reset and the driver will be re-enabled. The time-out value is set so that normal CAN communication will not cause the Dominant time-out circuit to expire.

#### **FAILSAFE**

If the bus-side power supply Vcc2 is lower than about 2.7V, the power shutdown circuits in the ISO1050 will disable the transceiver to prevent spurious transitions due to an unstable supply. If Vcc1 is still active when this occurs, the receiver output will go to a failsafe HIGH value in about 6 microseconds.

#### THERMAL SHUTDOWN

The ISO1050 has an internal thermal shutdown circuit that turns off the driver outputs when the internal temperature becomes too high for normal operation. This shutdown circuit prevents catastrophic failure due to short-circuit faults on the bus lines. If the device cools sufficiently after thermal shutdown, it will automatically re-enable, and may again rise in temperature if the bus fault is still present. Prolonged operation with thermal shutdown conditions may affect device reliability.

#### **BUS LOADING**

In the CAN standard ISO 11898-2 the driver differential output is specified with a  $60\Omega$  load (must be greater than 1.5V) and with a fully-loaded bus (must be greater than 1.2V). The ISO1050 is specified to meet the 1.5V requirement with a  $60\Omega$  load, and 1.4V with a  $45\Omega$  load. The differential input resistance of the ISO1050 is a minimum of  $30K\Omega$ . If the 167 transceivers are in parallel on a bus, this is equivalent to a  $180\Omega$  differential load. That transceiver load of  $180\Omega$  in parallel with the  $60\Omega$  (two  $120\Omega$  termination resistors) gives a total  $45\Omega$ . Therefore, the ISO1050 supports over 167 transceivers on a single bus segment, with margin to the 1.2V CAN requirement.



# **REVISION HISTORY**

Changes from Original (June 2009) to Revision A	Page
Added Typical 25-Year Life at Rated Working Voltage to Features	1
Added LIFE EXPECTANCY vs WORKING VOLTAGE section	12
Changes from Revision A (Sept 2009) to Revision B	Page
Added information that IEC 60747-5-2 and IEC61010-1 have been approved	1
Changed DW package from preview to production data	1
Added Insulation Characteristics and IEC 60664-1 Ratings tables	10
Added IEC file number	11
Added DW-16 thermal information table	
Changes from Revision B (June 2009) to Revision C	Page
Changed the IEC 60747-5-2 Features bullet From: DW package Approval Pending To: VDE approved for and DW packages	
• Changed the Minimum Interal Gap value from 0.008 to 0.014 in the Isolator Characteristics table	10
Changed V <sub>IORM</sub> Specification From: 1300 To: 1200 per VDE certification	10
Changed V <sub>PR</sub> Specification From 2438 To: 2250	10
Added the Bus Loading paragraph to the Application Information section	16

#### PACKAGE OPTION ADDENDUM



www.ti.com 10-Dec-2010

#### **PACKAGING INFORMATION**

Orderable Device	Status <sup>(1)</sup>	Package Type	Package Drawing	Pins	Package Qty	Eco Plan <sup>(2)</sup>	Lead/ Ball Finish	MSL Peak Temp <sup>(3)</sup>	Samples (Requires Login)
ISO1050DUB	ACTIVE	SOP	DUB	8	50	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-4-260C-72 HR	Contact TI Distributor or Sales Office
ISO1050DUBR	ACTIVE	SOP	DUB	8	350	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-4-260C-72 HR	Purchase Samples
ISO1050DW	ACTIVE	SOIC	DW	16	40	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-4-260C-72 HR	Purchase Samples
ISO1050DWR	ACTIVE	SOIC	DW	16	2000	Green (RoHS & no Sb/Br)	CU NIPDAU	Level-4-260C-72 HR	Purchase Samples

(1) The marketing status values are defined as follows:

ACTIVE: Product device recommended for new designs.

LIFEBUY: TI has announced that the device will be discontinued, and a lifetime-buy period is in effect.

NRND: Not recommended for new designs. Device is in production to support existing customers, but TI does not recommend using this part in a new design.

PREVIEW: Device has been announced but is not in production. Samples may or may not be available.

**OBSOLETE:** TI has discontinued the production of the device.

(2) Eco Plan - The planned eco-friendly classification: Pb-Free (RoHS), Pb-Free (RoHS Exempt), or Green (RoHS & no Sb/Br) - please check http://www.ti.com/productcontent for the latest availability information and additional product content details.

**TBD:** The Pb-Free/Green conversion plan has not been defined.

**Pb-Free** (RoHS): TI's terms "Lead-Free" or "Pb-Free" mean semiconductor products that are compatible with the current RoHS requirements for all 6 substances, including the requirement that lead not exceed 0.1% by weight in homogeneous materials. Where designed to be soldered at high temperatures, TI Pb-Free products are suitable for use in specified lead-free processes. **Pb-Free** (RoHS Exempt): This component has a RoHS exemption for either 1) lead-based flip-chip solder bumps used between the die and package, or 2) lead-based die adhesive used between the die and leadframe. The component is otherwise considered Pb-Free (RoHS compatible) as defined above.

Green (RoHS & no Sb/Br): TI defines "Green" to mean Pb-Free (RoHS compatible), and free of Bromine (Br) and Antimony (Sb) based flame retardants (Br or Sb do not exceed 0.1% by weight in homogeneous material)

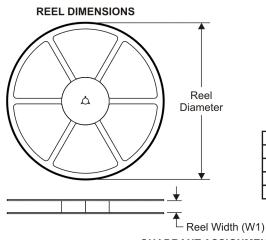
(3) MSL, Peak Temp. -- The Moisture Sensitivity Level rating according to the JEDEC industry standard classifications, and peak solder temperature.

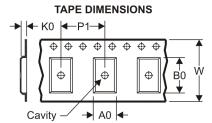
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www.ti.com 6-Jan-2011

#### TAPE AND REEL INFORMATION





A0	Dimension designed to accommodate the component width
B0	Dimension designed to accommodate the component length
K0	Dimension designed to accommodate the component thickness
W	Overall width of the carrier tape
P1	Pitch between successive cavity centers

#### QUADRANT ASSIGNMENTS FOR PIN 1 ORIENTATION IN TAPE



#### \*All dimensions are nominal

Device	Package Type	Package Drawing			Reel Diameter (mm)	Reel Width W1 (mm)	A0 (mm)	B0 (mm)	K0 (mm)	P1 (mm)	W (mm)	Pin1 Quadrant
ISO1050DUBR	SOP	DUB	8	350	330.0	24.4	10.9	10.01	5.85	16.0	24.0	Q1



PACKAGE MATERIALS INFORMATION

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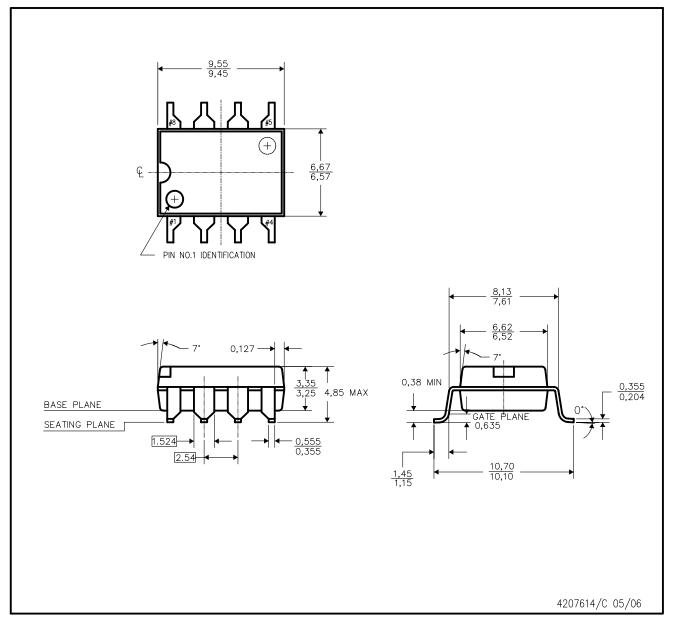


#### \*All dimensions are nominal

Device	Package Type	Package Drawing	Pins	SPQ	Length (mm)	Width (mm)	Height (mm)
ISO1050DUBR	SOP	DUB	8	350	358.0	335.0	35.0

# DUB (R-PDSO-G8)

# PLASTIC SMALL-OUTLINE



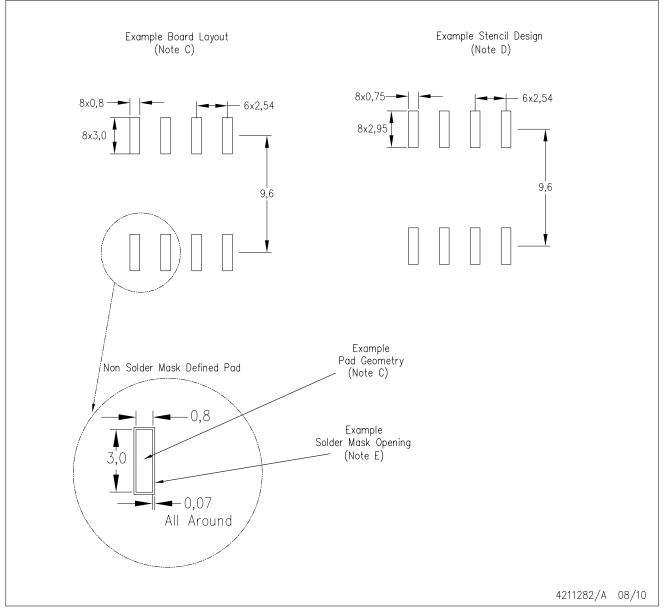
NOTES: A. All linear dimensions are in millimeters. Dimensioning and tolerancing per ANSI Y14.5 M-1982.

B. This drawing is subject to change without notice.

C. Dimensions do not include mold flash or protrusions. Mold flash or protrusions shall not exceed 0.254mm.

DUB (R-PDSO-G8)

# PLASTIC SMALL OUTLINE

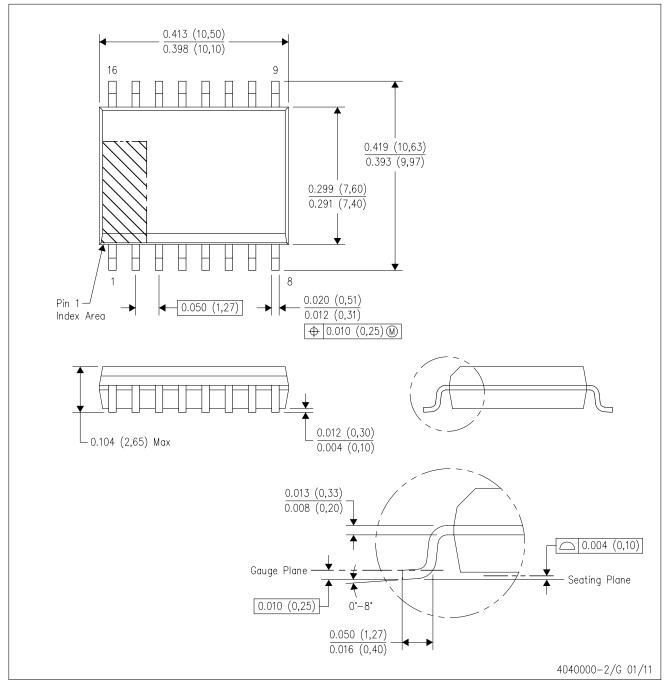


NOTES: A. All linear dimensions are in millimeters.

- B. This drawing is subject to change without notice.
- C. Publication IPC-7351 is recommended for alternate designs.
- D. Laser cutting apertures with trapezoidal walls and also rounding corners will offer better paste release. Customers should contact their board assembly site for stencil design recommendations. Refer to IPC-7525.
- E. Customers should contact their board fabrication site for solder mask tolerances between and around signal pads.

DW (R-PDSO-G16)

PLASTIC SMALL OUTLINE



NOTES: A. All linear dimensions are in inches (millimeters). Dimensioning and tolerancing per ASME Y14.5M-1994.

- B. This drawing is subject to change without notice.
- C. Body dimensions do not include mold flash or protrusion not to exceed 0.006 (0,15).
- D. Falls within JEDEC MS-013 variation AA.



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